

## B.Tech IV Year I Semester (R13) Supplementary Examinations June 2017 SWITCHED MODE POWER CONVERTERS

(Electrical and Electronics Engineering)

Time: 3 hours

PART – A

(Compulsory Question)

1 Answer the following:  $(10 \times 02 = 20 \text{ Marks})$ 

- (a) Explain the principle of volt second balance in inductors.
- (b) Obtain the input-output voltage as a function of duty ratio for a Buck-Boost dc-dc converter in continuous conduction mode.
- (c) List out the difference between fly back and push pull topologies.
- (d) Discuss why transformer isolations are needed in high frequency power conversion.
- (e) List the various classifications of resonant converters.
- (f) What is meant by zero voltage switching?
- (g) Explain the significance of small signal modeling in DC-DC converters.
- (h) List out the dynamic performance indices of DC-DC converters.
- (i) List out the controller specifications.
- (j) Why, frequency domain analysis is important in controller design?

# PART - B(Answer all five units, 5 X 10 = 50 Marks) UNIT - I

- 2 (a) Illustrate the operation of step down converter in continuous conduction mode and derive an expression for the ripple voltage.
  - (b) Calculate  $V_2$  for a given wave form in DC steady state.



OR

3 Explain the operation of CUK converter and derive output voltage equation.

#### UNIT – II

- 4 (a) Draw the circuit and explain the operation of fly back converter.
- (b) Compare Isolated and non-isolated switched mode converters.

#### OR

5 Draw the circuit diagram and explain the operation of a full bridge push pull converter and draw the load current and load voltage waveform.

## UNIT – III

6 Discuss the operation of parallel resonant dc-dc converter with the help of circuit diagram.

#### OR

7 Analyze and obtain the output voltage of L - type boost converter.

## UNIT – IV

8 Obtain the steady state solution of the non-ideal boost converter by using its average model.

OR

9 Obtain the transfer function of buck converter using its equivalent circuit.

## UNIT – V

- Discuss about the point oller specifications for design of going oller. O. IN
- 11 Explain about the design of proportional, Integral and derivative controller.

Max. Marks: 70