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Max. Marks: 70

# B.Tech IV Year I Semester (R13) Supplementary Examinations June 2017 COMPUTER CONTROL OF PROCESS

(Electronics & Instrumentation Engineering)

Time: 3 hours

# PART – A

#### (Compulsory Question)

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Answer the following: (10 X 02 = 20 Marks)

- (a) What are the applications of PLC?
- (b) What is the need of computer in control process?
- (c) State the advantages of PLC.
- (d) List the different types of outputs available in a PLC.
- (e) Write the features of a digital PID controller.
- (f) Write about the sequencer functions in PLC.
- (g) What is sampler and hold?
- (h) What is pulse transfer function?
- (i) What is dead time compensation?
- (j) State the theoretical properties required for a digital control algorithm.

#### PART – B

(Answer all five units, 5 X 10 = 50 Marks)

#### ( UNIT – I )

2 Explain in detail about input/output modules of PLC.

### OR

3 List different types of isolators and explain the functions of an optical isolator in detail.

# UNIT – II )

- 4 Explain the following:
  - (a) Timer and counters in PLC.
  - (b) Input / output modules in PLC.
- 5 Explain in detail the basic building blocks of PLC.
  - UNIT III

- 6 Explain the following:
  - (a) Analog PLC operation.
  - (b) MCR functions.
- 7 Write about:

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- (a) Networking of PLC.
- (b) PID functions.

#### UNIT – IV

OR

- 8 Explain the following:
  - (a) Open loop response of sampled data control system.
  - (b) Closed loop response of sampled data control system.
- 9 What is Z transform? List its properties.

## UNIT – V

OR

10 Explain Dahlin's method in detail.

WWW . MANARE **S**ULTS . CO . IN Design a Deadbeat controller for the following system:  $G_p(S) = \frac{2e^{-2S}}{4s+1}$ ; T = 1 sec