

Total No. of Questions : 10]

SEAT No. :

P3503

[Total No. of Pages : 4

[5560]-152

T.E. (E & TC)

DIGITAL SIGNAL PROCESSING

(2012 Course) (304182)

Time : 2½ Hours]

[Max. Marks : 70

Instructions to the candidates:

- 1) *Answer all questions.*
- 2) *Figures to the right indicate full marks.*

Q1) a) Draw the spectrum for three Nyquist cases of sampling as

- i) $f_s > 2 f_{\max}$
- ii) $f_{\max} < f_s < 2 f_{\max}$
- iii) $f_s < f_{\max}$

with respect of frequency axis. **[6]**

- b) i) Write analysis and synthesis equations for DTFT. Write down its basis function.
- ii) What is orthogonality? Write its application. **[4]**

OR

Q2) a) Calculate 4-point DFT using DIT-FFT algorithm for $x(n)=2^{(2n)}$ **[6]**

b) Find $X(5)$, $X(6)$, & $X(7)$ for given 8-point DFT,

$$X(k) = \{20, -5.82 - 2.41j, 0, -0.17 - 0.41j, 0, _, _, _, \}$$

Which property did you use for writing remaining three values? **[4]**

Q3) a) Draw the ROC for

- i) Stable & causal
- ii) Stable & non-causal
- iii) Unstable & causal

IIR systems. **[6]**

- b) Write any two properties of DFT along with their mathematical equations. **[4]**

OR

P.T.O.

Q4) a) Determine the system function $H(Z)$ of

$$y(n) + \frac{3}{4}y(n-1) + \frac{1}{8}y(n-2) = x(n) + x(n-1).$$

Show poles & zeros in Z-plane. [6]

b) Calculate Z-transform of

$$x(n) = \left(\frac{1}{4}\right)^{(n-1)}. \text{ Draw ROC. [4]}$$

Q5) a) i) Convert the analog filter with system function,

$$H_a(S) = \frac{S + 0.1}{(S + 0.1)^2 + 16}$$

into a digital IIR filter by means of the Bilinear Transformation. The digital filter is to have a resonant frequency of $\omega_r = \pi/2$.

ii) Implement this filter using Direct form - II structure. [8]

b) Draw the labelled magnitude response for

i) Butterworth LPF

ii) Chebyshev Type I & Type II LPF

Show f_p , f_c , f_s in the diagram. [8]

OR

Q6) a) i) Write the substitutions for 'S' for

1) Approximation of derivatives

2) Impulse Invariance

3) Bilinear Transformations

to convert the analog TF to digital TF (transfer function)

ii) State one advantage & one limitation of Impulse Invariance Method.

[8]

- b) Realize the
- i) Cascade &
 - ii) Parallel form
- structure for the given TF :

$$H(Z) = \frac{\left(1 - \frac{1}{2}Z^{-1}\right)}{\left(1 - \frac{1}{4}Z^{-1}\right)\left(1 + \frac{1}{4}Z^{-1}\right)} \quad [8]$$

- Q7)** a) Determine a Direct form realization for the following linear phase filters
- i) $h(n) = \{1, 2, 3, 4, 3, 2, 1\}$
 - ii) $h(n) = \{1, 2, 3, 3, 2, 1\}$ [8]
- b) Write expressions for
- i) Phase delay
 - ii) Group delay
 - iii) Linearity condition for symmetrical & antisymmetrical FIR systems. [8]

Draw

- i) Symmetric and
- ii) Asymmetric impulse responses

OR

- Q8)** a) i) What are the possible types of impulse response for linear phase FIR filters?
- ii) The frequency response of a digital filter is

$$H(e^{jw}) = (0.4 + 0.7 \cos 2w - 0.5 \cos 4w) \cdot e^{-j(0.3\pi + 4w)}$$

Determine the phase delay and group delay. [8]

- b) Design a linear phase FIR low pass filter using rectangular window by taking 7 samples of window sequence, and with a cut-off frequency, $W_c = 0.2\pi$ rad/sample.

Implement the above designed FIR LPF using linear phase structure.

[8]

- Q9)** a) i) Draw block schematic for
- 1) Decimation
 - 2) Interpolation
- ii) Consider the discrete time signal,

$$x(n) = \{1, 2, 3, 4, 5, 6, 7, 8, 9, 10\}$$

Determine the result of the signal when

- 1) $D = 2$ &
- 2) $I = 3$
- 3) $I = 2$

[9]

- b) Discuss:
- i) DMA
 - ii) MAC and
 - iii) VLIW architecture

[9]

OR

Q10) Write short notes on:

[18]

- i) Music signal processing
- ii) Image processing
- iii) Radar signal processing

