SEAT No.	:	
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P3660

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## APR - 15 / Engg. - 145

## T.E. (Computer Engineering) (In Sem - Semester - II) DIGITAL SIGNAL PROCESSING APPLICATIONS (2012 Pattern)

Time: 1 Hour] [Max. Marks: 30

Instructions to the candidates:

- 1) Attempt Q.1 or Q.2, Q.3 or Q.4, Q.5 or Q.6.
- 2) Neat diagrams must be drawn wherever necessary.
- 3) Figures to the right indicate full marks.
- 4) Assume suitable data, if necessary.
- Q1) a) Why the problem of aliasing is observed during the sampling process? Derive the relationship between analog frequency F and DT frequency f.[5]
  - b) State the advantages of Digital Signal Processing and give the classification of DT signals. [5]

OR

Q2) a) Define the impulse response of a system and obtain it for a system described as [5]

$$y(n) = x(n) + 0.5 y(n-1)$$

- b) Represent a DT sequence x(n) using convolution. Obtain the computational complexity of linear convolution of two DT signals having N samples each. [5]
- **Q3)** a) State and prove:

[5]

- i) time reversal and
- ii) time shifting property of a FT.
- b) State the necessary condition for the existence of FT. Explain how the magnitude response of a FT is obtained? Obtain DT frequencies {ωk} for 8-point DFT.

OR

P.T.O.

- **Q4)** a) Obtain 4 point DFT for a sequence  $x(n) = \{1,-2,2,1\}$  and plot the magnitude spectrum. [5]
  - b) Discuss the periodicity and circular shifting property of N point DFT. How convolution property of DFT is different than FT? [5]
- **Q5)** a) Obtain ZT of a DT signal using ZT properties where, x(n)=2n.u(n-1) [5]
  - b) Derive the relationship between ZT and FT. [5]

OR

- **Q6)** a) Obtain ZT of two standard signals u(n) and  $\delta(n)$ . Plot its ROCs. [5]
  - b) Define a system function H(Z). How it describes the properties of DT system? What is pole zero plot? [5]

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